

# Making sense of sensors

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**FABRICADEMY**  
textile and technology academy

# Required materials

## Option 1 - Buy it yourself or reuse arduino kits

[Arduino Compatible Board](#)

(any brand will work, but Leonardo can act as a keyboard)

[LDR light sensor](#)

(photoresistor)

[Temperature sensor](#) (i.e. TMP36)

[Adafruit LIS3DH](#) Triple-Axis

Accelerometer (or similar)

[NeoPixels](#)

## Option 2 - Flora Kits

[FLORA Sensor Pack](#)

[LDR light sensor](#)

[NeoPixels](#)

## Option 3 - All in one

**Cheaper & recommended**

[Adafruit Circuit](#)

[playground](#)

# What is a sensor?

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Anything that can measure some natural phenomena

# Many different kind of sensors

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Sensors can be classified based on:

- Which **natural quantity** is measured
- The measurement **precision**
- The kind of output: **analog** vs **digital**

# Sensor types

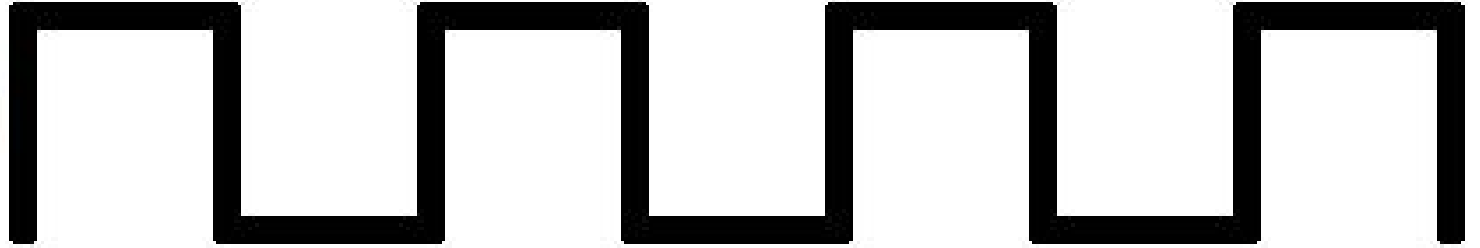
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- **Acoustic, sound, vibration:** microphone, etc
- **Automotive:** speed, air flow, knock
- **Chemical:** gas, etc
- **Electricity,** Fluids Flow, Radiation
- **Environment:** pressure, temperature, moisture, etc
- **Navigation:** gyroscope, compass, altitute
- **Position:** capacitive, accelerometer, photoelectric, rotary encoders, PIR, flexure, stretch, etc
- **Force, Proximity,** etc

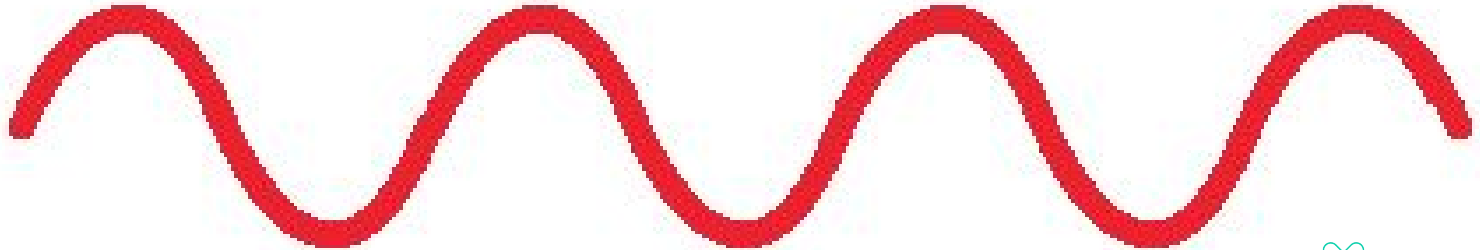
# Analog vs Digital Sensors

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**Digital**

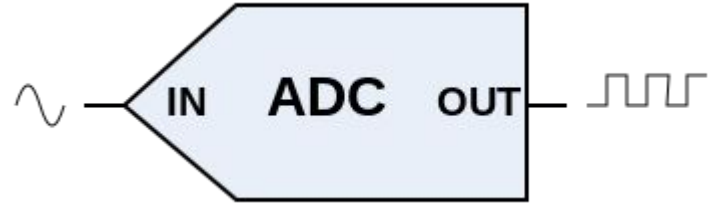


**Analog**



# Analog to digital conversion

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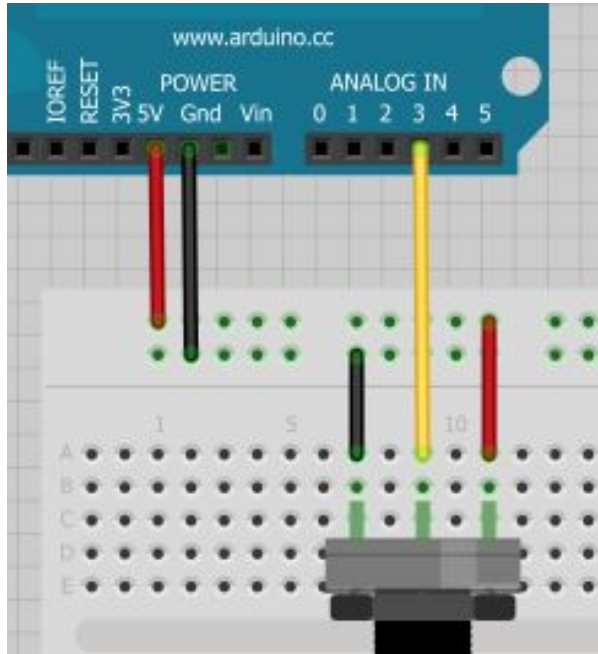
**Analog to Digital Converter (ADC)** is a part of almost any micro-controller.

It helps you to **convert analog inputs** (coming from a sensor) to **a digital stream** of 0 and 1.

It does this comparing the Voltage read on a PIN with the AREF (analog reference voltage)

# Analog sensor with Arduino: an example

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```
// Set the PIN A3 as input
pinMode(A3, INPUT);
// Read in a value
int x = analogRead(A3);
// Print it to the serial console
Serial.println("Analog Reading")
Serial.println(x)
// will be a number from 0 to 1023
// representing the voltage we read
```





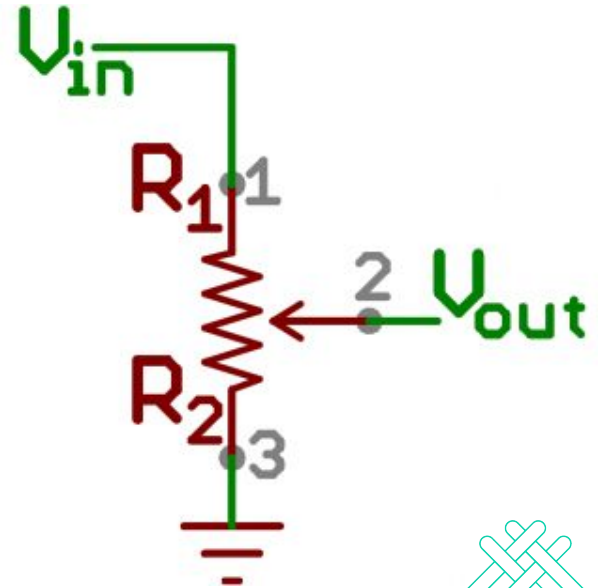
# Resistive sensors: voltage divider

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The ADC can only measure voltage, many sensors are Resistive.

Resistance is limiting the amount of current passing in a circuit.

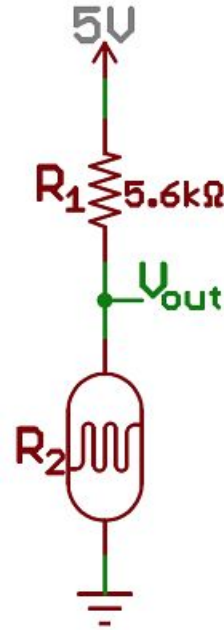
We can measure resistance using a **voltage divider**

$$V_{out} = V_{in} \cdot \frac{R_2}{R_1 + R_2}$$

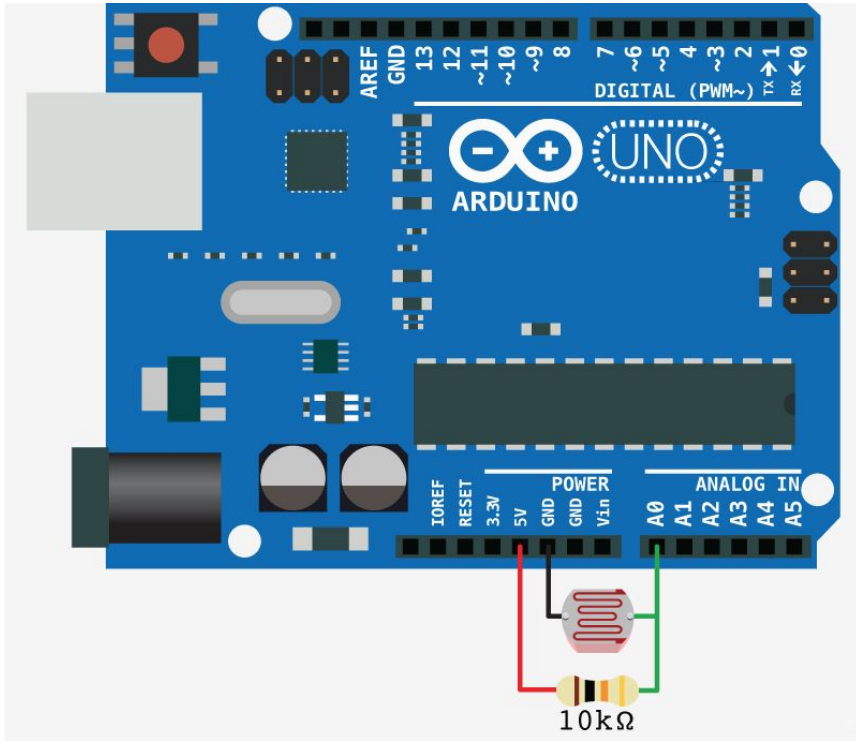


# Voltage divider example

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We use a **photoresistor** which has a variable resistance based on the amount of light it is exposed



Light Level	$R_2$ (Sensor)	$R_1$ (Fixed)	Ratio $R_2/(R_1+R_2)$	$V_{out}$
Light	$1\text{k}\Omega$	$5.6\text{k}\Omega$	0.15	0.76 V
Dim	$7\text{k}\Omega$	$5.6\text{k}\Omega$	0.56	2.78 V
Dark	$10\text{k}\Omega$	$5.6\text{k}\Omega$	0.67	3.21 V



## Wiring & Arduino Code

```
int LDR_Pin = A0; //analog pin 0

void setup(){
  Serial.begin(9600);
}

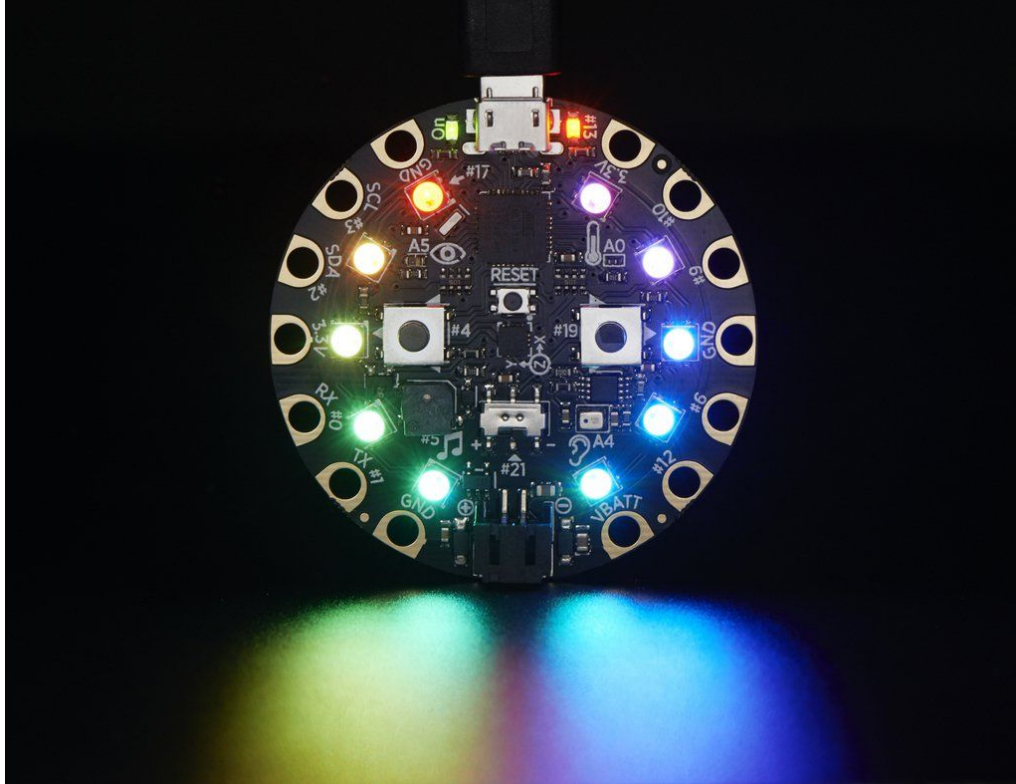
void loop(){
  int LDRReading = analogRead(LDR_Pin);
  Serial.println(LDRReading);
  delay(250);
}
```

Exercise:

Print "Dark" when lights go down,  
Print "Light" when sensor is in bright light,  
Print "Shade" otherwise

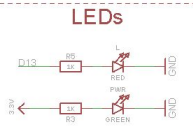
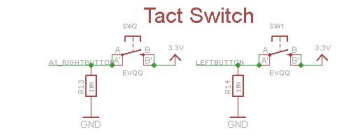
# Adafruit Circuit Playground

[Windows Drivers Here!](#)

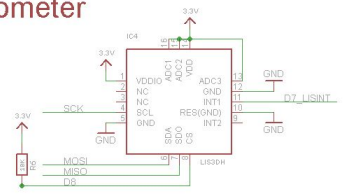


Arduino - compatible board, with many sensors integrated, no soldering required!

Accelerometer  
Light sensor  
Temperature  
Microphone  
Buzzer  
RGB LEDs  
Buttons



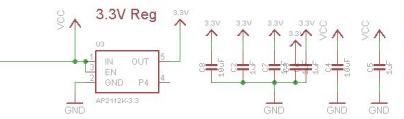
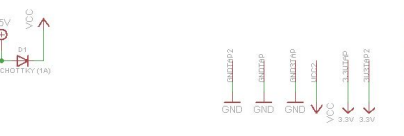
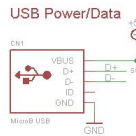
## Accelerometer



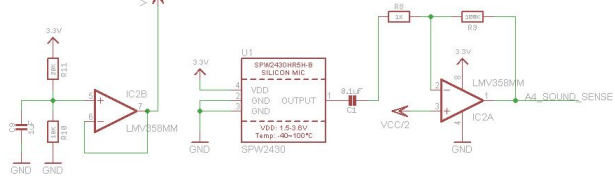
## Slide Switch



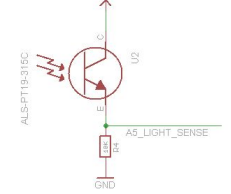
## POWER SUPPLY



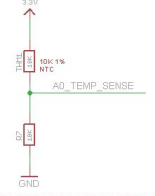
## Sound Sensor



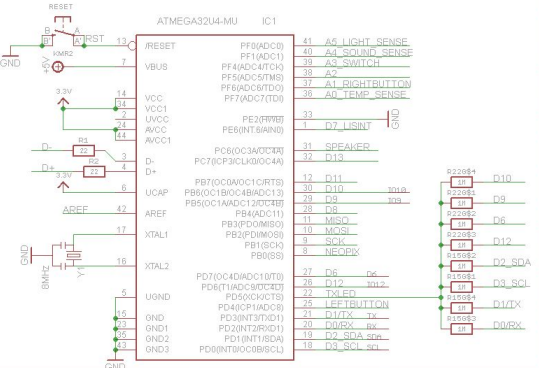
## Light Sensor



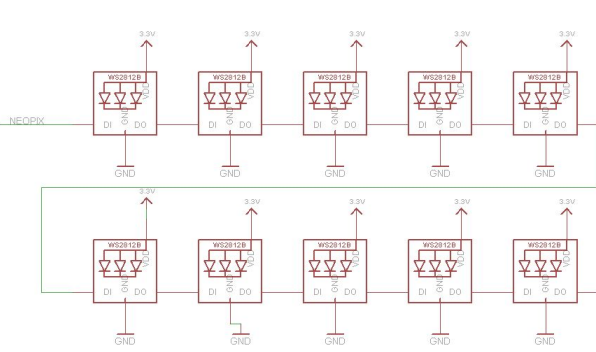
## Temp Sensor



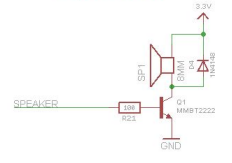
## ATMEGA32u4 MICROCONTROLLER



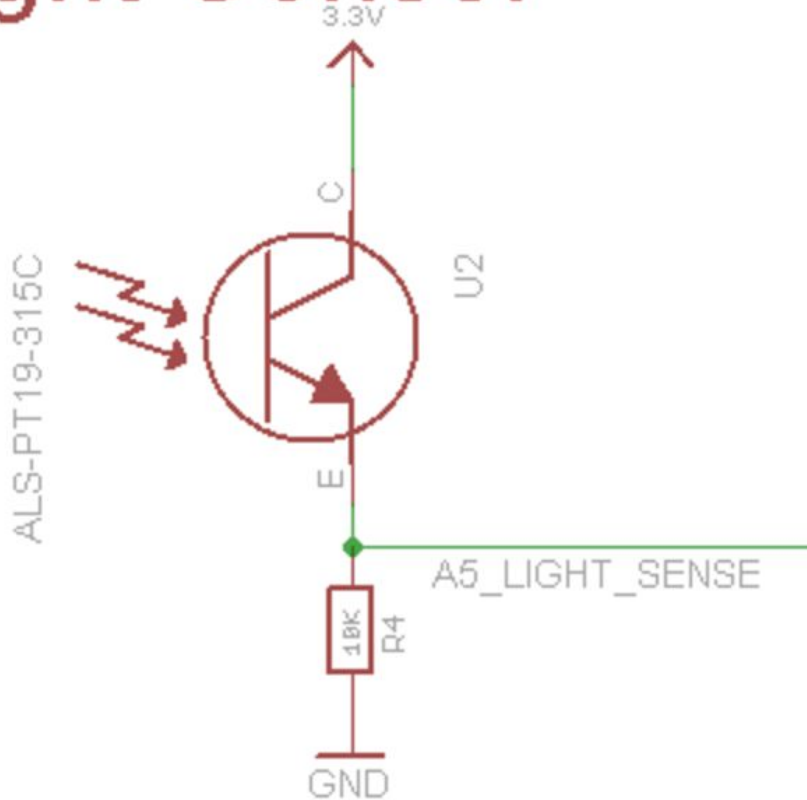
## NeoPixels



## Speaker

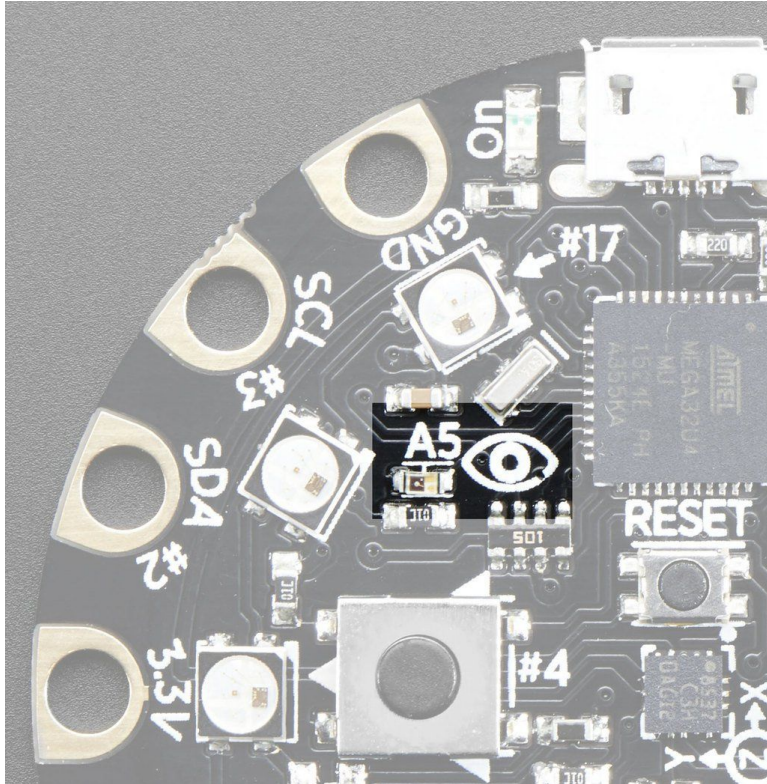


# Light Sensor



On the Circuit Playground schematics you can see that this **sensor is connected to analog pin #A5**

# Light sensor



This sensor is connected to analog pin #A5

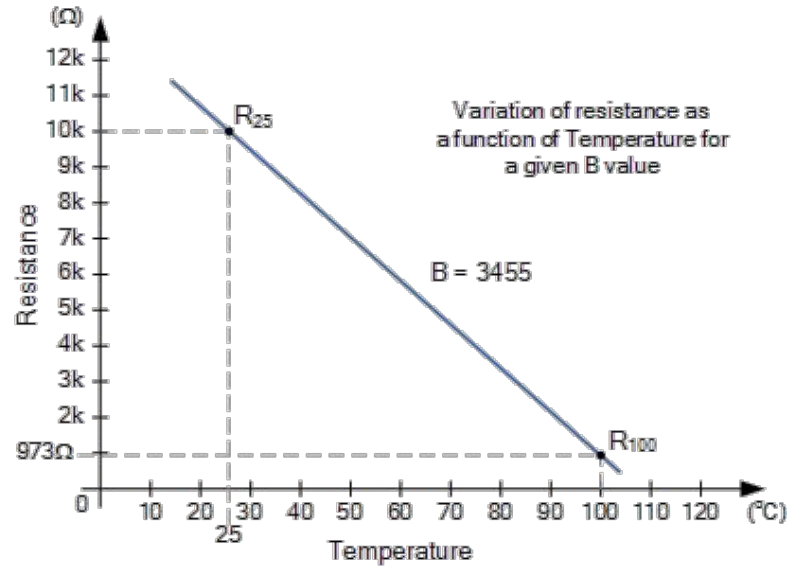
Will read between 0 and 1023 with higher values corresponding to higher light levels.

A reading of about 300 is common for most indoor light levels.

# Sensing temperature

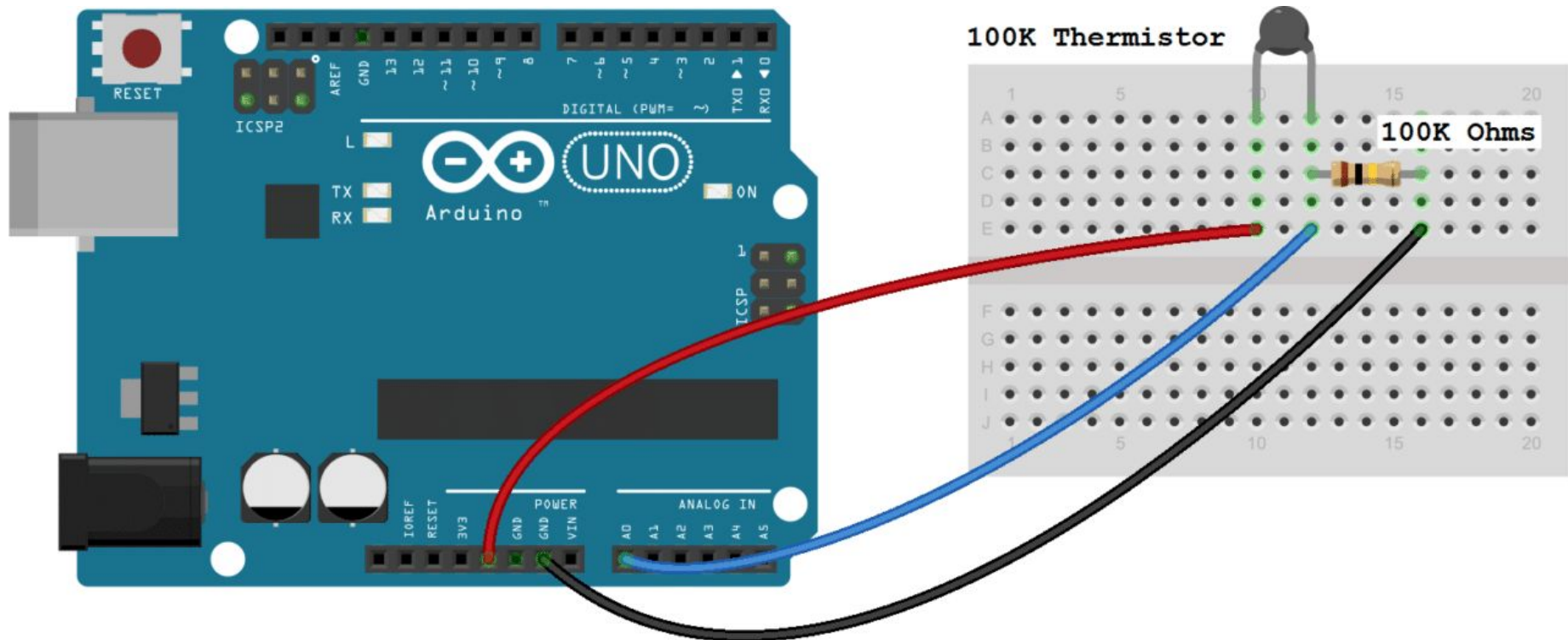
A thermistor is a resistor that changes its resistance based on the temperature

The higher the temperature the lower the resistance

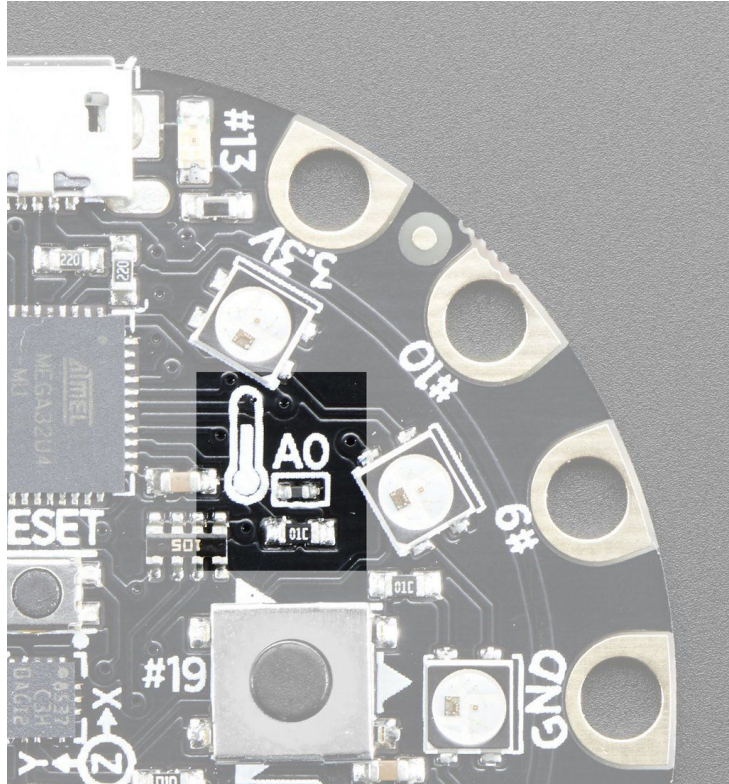




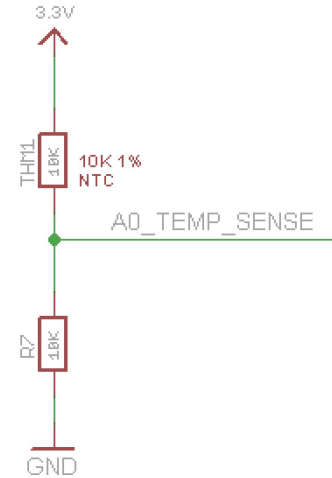
# Wiring



# Temperature sensor



## Temp Sensor



On the Circuit Playground schematics you can see that this **sensor is connected to analog pin #A0**

# Code

Code is the same as  
Light Sensor.

We have a linear voltage  
reading that can be  
mapped to C or F with  
 $\pm 0.25^{\circ}\text{C}$  accuracy

But we can also use the  
voltage only less precise  
reading: i.e. hot / cold

```
int NTC_Pin = A0; //analog pin 0

void setup(){

    Serial.begin(9600);

}

void loop(){

    int NTCReading = analogRead(NTC_Pin);
    Serial.println(NTCReading);
    delay(250);

}
```

# Checking the actual temperature

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## HARD WAY

- 1) Read the sensor analog voltage
- 2) Convert it to resistance, using the voltage divider formula
- 3) Take several readings and make an average
- 4) Optionally use 3V3 as AREF, for less noisy reading
- 5) Map the resistance to the C or F using the [Steinhart-Hart equation](#)

[Check out this article for more details](#)

# Checking the actual temperature

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## EASY WAY

```
#include <Adafruit_CircuitPlayground.h>

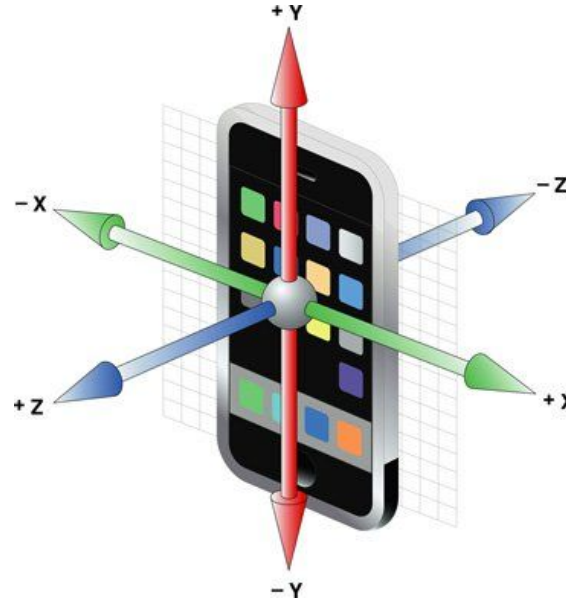
void setup() {
  Serial.begin(9600);
  CircuitPlayground.begin();
}

void loop() {
  Float temp;
  temp = CircuitPlayground.temperature();
  Serial.println(temp);
}
```

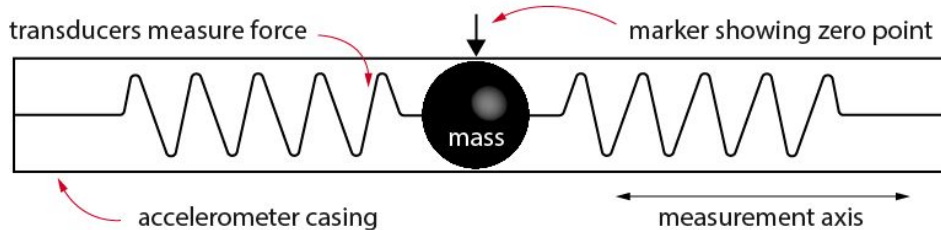
[Thermistor Arduino Library for other boards, and generic sensors](#)

# Accelerometers

Accelerometers are devices that measure [acceleration](#), which is the rate of change of the [velocity](#) of an object.



## Accelerometer

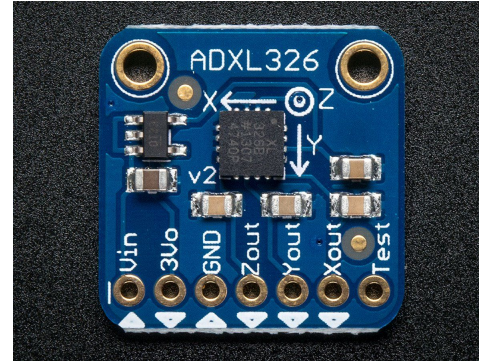


Micro-Electro-Mechanical Sensors (MEMS)  
Inside there's usually a mass that moves and transducers that move the force of movement

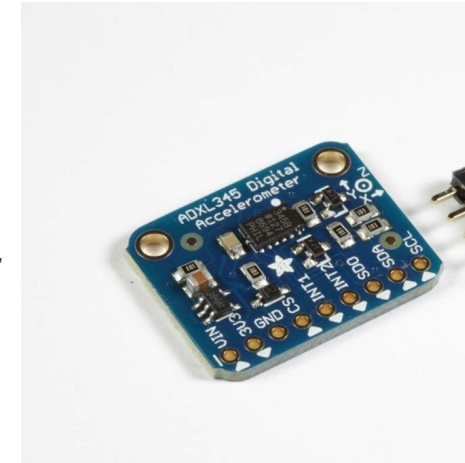
# Choosing an accelerometer

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**Analog vs digital:** Analog accelerometers output a constant **variable voltage** depending on the amount of acceleration applied. Digital ones output their value with **PWM** or using multi-wire digital protocols such as **I2C** or **SPI**.

**Precision range, Number of Axes, bandwidth, etc**

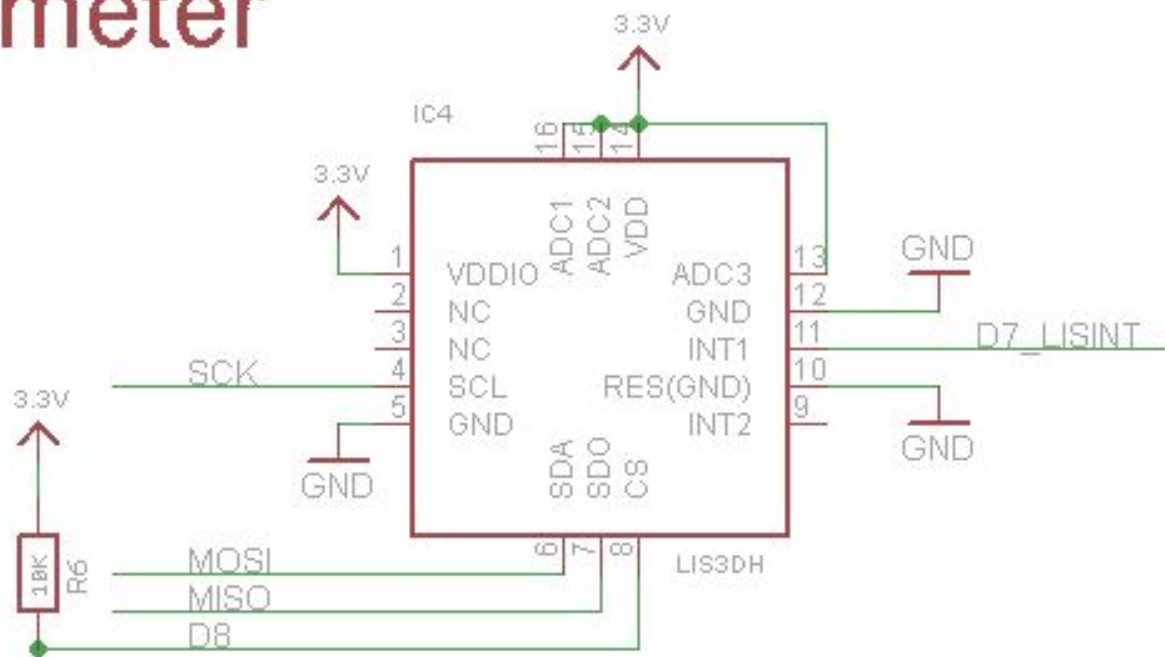


**Analog accelerometer  
ADXL326**



**Digital  
accelerometer  
ADXL345  
I2C**

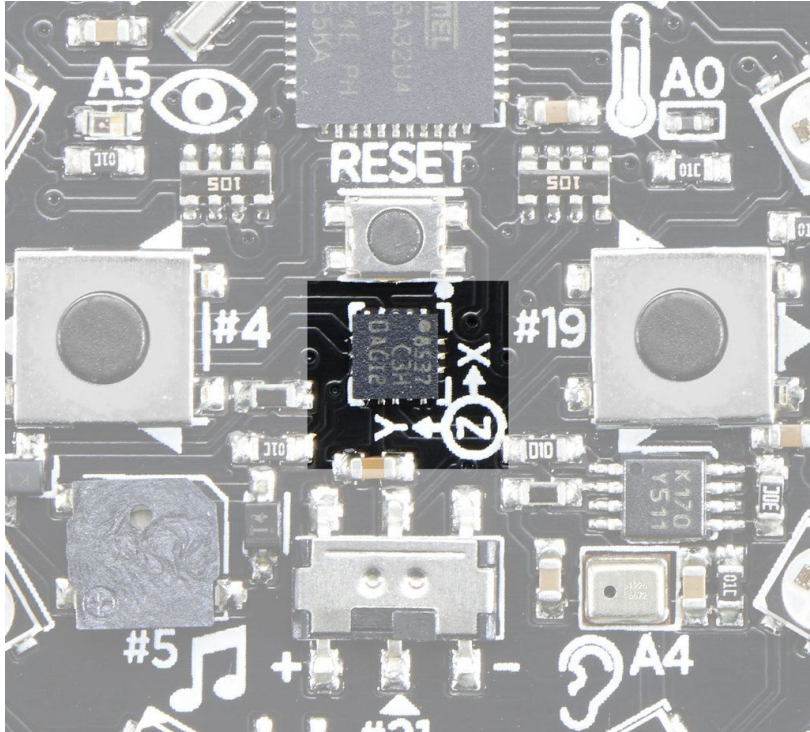
# Accelerometer





# Accelerometer

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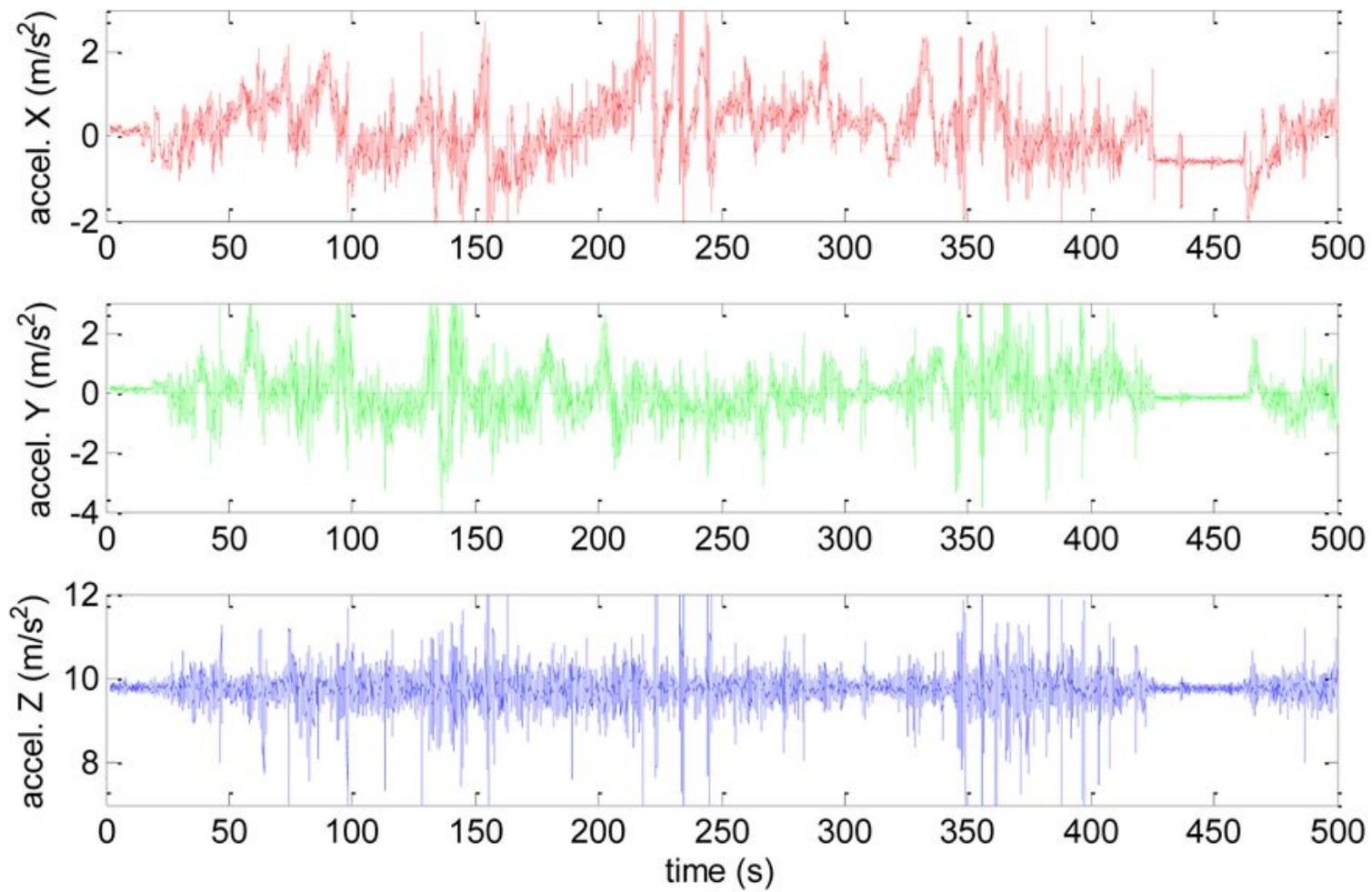
The CircuitPlayground has a model that can sense  $\pm 2g$ ,  $4g$ ,  $8g$  ( $g = 9.8 \text{ meters/s}^2$ )

The sensor is **more precise** when you set it to  $2g$ , less when you set it to  $8g$

It also has **tap detection** (1 or 2 taps)

So you can easily detect these small movements in hardware

### Accelerometer readings



# Interpreting readings

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Any accelerometer will give you a **stream of x,y,z readings**.

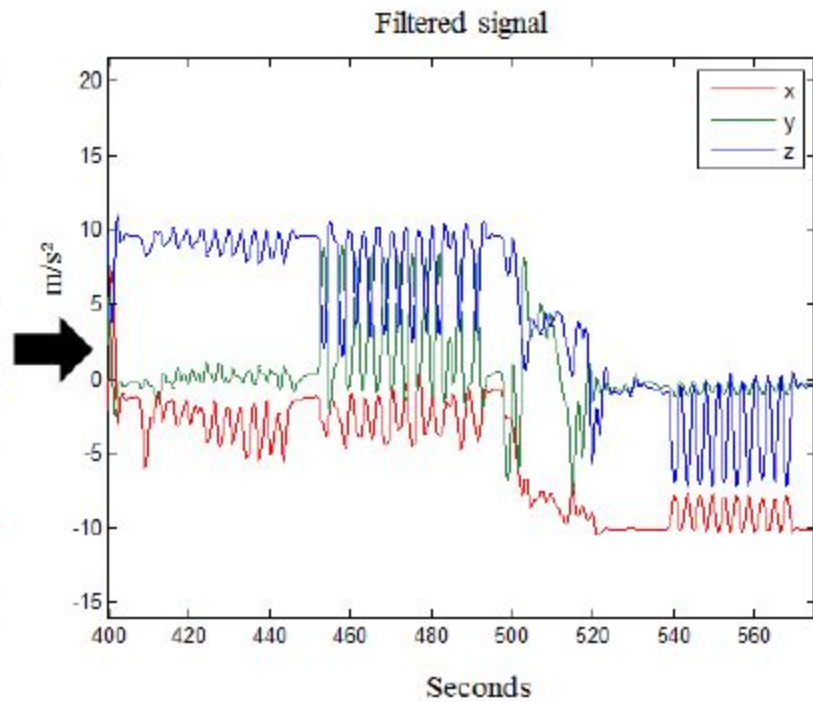
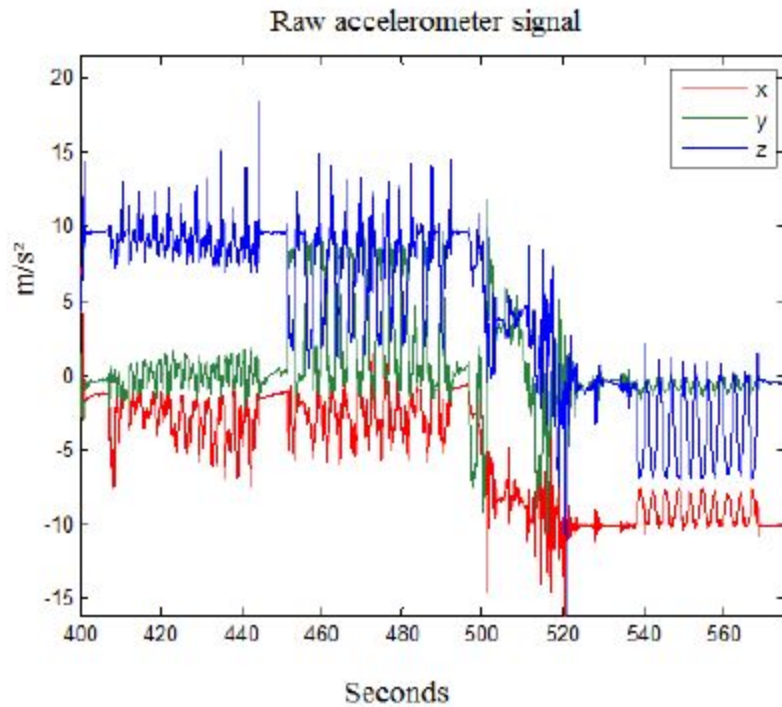
This will be **very noisy**, as the accelerometer is **very sensitive**.

Only **standing still** will get you **(0,0,0)**

Also we must **remove gravity** from our readings.

This can be done with a [low-pass filter](#), which uses previous readings and a threshold to smooth out our signals

# Raw vs filtered



# Basic low pass filter

**`filtered_output[i] =  $\alpha$ *raw_input[i] + (1- $\alpha$ )*filtered_output[i-1]`**

$\alpha$  is the threshold between 0 and 1  
and we can use it to adjust the  
sensitivity of the filter

[This is an exponential weighted moving average, read more here](#)

# Arduino function

```
int smooth(int data, float filterVal, float smoothedVal){

    // check to make sure param's are within range

    if (filterVal > 1){
        filterVal = .99;
    }
    else if (filterVal <= 0){
        filterVal = 0;
    }

    smoothedVal = (data * (1 - filterVal)) + (smoothedVal * filterVal);

    return (int)smoothedVal;
}
```

# Detecting motion

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Once we smooth the data we can detect motion in different ways:

- **Amplitude of change** - how much acceleration changes on one or more axis during a period of time, good for shake
- **Comparing** data taken from samples (training corpus) to the one we read from the sensors

The second method is more complex and require some processing power.

If you need to recognize gestures, the following methods are proven to work:

- [Hidden Markov Models](#)
- [Dynamic time warping](#)
- [1\\$ Gesture recognizer](#)